Veronte Link

Release 6.14.60/1.0

Embention Sistemas Inteligentes, S.A.

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Scope of Changes

- Version 1.0
 - Added:
 - Buffer size parameter description in UDP, TCP-Server and TCP-Client connections
 - Warning about set up and operation with a Veronte Autopilot 1x via Cloud in the Cloud connection section
 - Software Changelog between version 6.14.28 and 6.14.60
 - Changed:
 - Configuration status descriptions updated to v6.14.60 (Operation section)
 - Clarification on Error when replaying a session troubleshooting

Quick Start

Veronte Link establishes **communication between a computer and any Veronte product** by creating a **VCP bridge**. It allows to use multiple control stations and autopilots to be interconnected, operating simultaneously.

Veronte Link also includes a **post-flight viewer**, to reproduce all recorded data from previous flights and generate plots and reports.

Veronte Link supports Windows operating system.

(i) Note

Windows 10 is recommended, but Windows 11 is supported.

System Requirements

Before executing this software, users should check the following sections with the minimum and recommended PC hardware requirements.

Minimum requirements

- CPU: Intel Core i5-8365UE
- RAM: 8 GB DDR4
- STO: 256 GB SSD

Recommended requirements

- CPU: 12th Gen Intel(R) Core(TM) i7-12700H 14 cores up to 4,70 GHz
- RAM: 32,0 GB
- STO: 1TB SSD M.2 NVMe PCIe

Installation

Once a Veronte device has been purchased, a GitHub release should be created for the customer with the application.

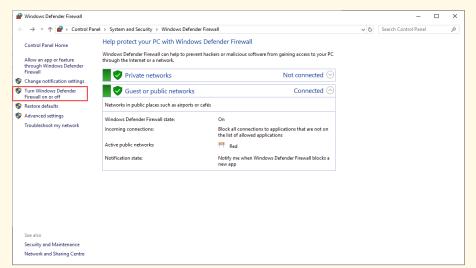
To access to the release and download the software, read the Releases section of the **Joint Collaboration Framework** manual.

To install **Veronte Link** on Windows, execute Veronte Link.exe and follow the indications of the Setup Wizard.

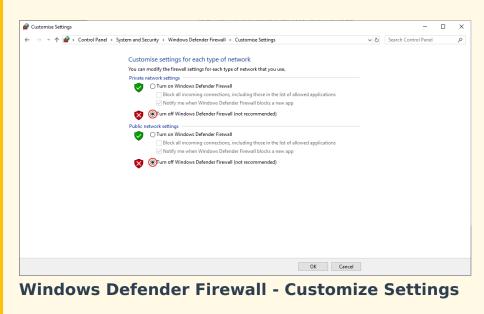
△ Warning

In case of any issue during installation, please disable Windows Defender and Firewall.

To disable Firewall, go to "Control Panel" and "Firewall of windows", then click on **Turn off**.



Windows Defender Firewall



Additional apps

Veronte UDP Telemetry CLI



Veronte UDP Telemetry CLI

Veronte UDP Telemetry CLI is an additional command-line tool which allows **Veronte Link** to send Autopilot 1x telemetry over UDP.

Download

Once the **Veronte Autopilot 1x** has been purchased, a GitHub release should be created for the customer with the application.

To access to the release and download the software, read the Releases section of the **Joint Collaboration Framework** manual.

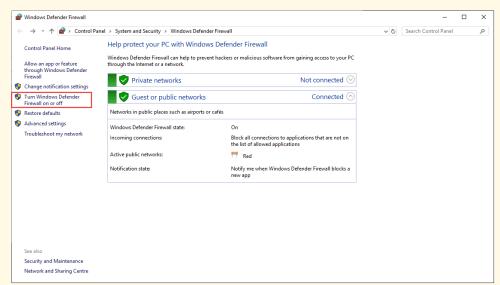
Installation

To install **Veronte UDP Telemetry CLI** on Windows just execute "veronte-udptelemetry-cli.exe" and follow the indications of the Setup Wizard.

△ Warning

If users have any problems with the installation, please disable the antivirus and the Windows firewall. Disabling the antivirus depends on the antivirus software.

To disable the firewall, go to "Control Panel" \rightarrow "System and Security" \rightarrow "Windows Defender Firewall" and then, click on "Turn windows Defender Firewall on or off".



Windows Defender Firewall

ustomise Settings		-	
→ ↑ Panel → System and Security → Windows Defender Firewall → Customise Settings	~ Ō	Search Control Panel	
Customise settings for each type of network			
You can modify the firewall settings for each type of network that you use.			
Private network settings			
O Turn on Windows Defender Firewall			
Block all incoming connections, including those in the list of allowed applications			
✓ Notify me when Windows Defender Firewall blocks a new app			
🚫 🎯 Turn off Windows Defender Firewall (not recommended)			
Public network settings			
O Turn on Windows Defender Firewall			
Block all incoming connections, including those in the list of allowed applications			
Notify me when Windows Defender Firewall blocks a new app			
((i))Turn off Windows Defender Firewall (not recommended)			
• •			
OK Cancel			
indows Defender Firewall: Customize			 -

Configuration

The following sections detail the steps to **configure** the Veronte system to transmit telemetry UDP messages through **Veronte UDP Telemetry CLI**, after it is installed.

1x PDI Builder

First, in **1x PDI Builder**, the intended variables to send must be added to the corresponding telemetry vector.

To do this:

- 1. Go to Telemetry menu \rightarrow **Telemetry panel**.
- By clicking the corresponding + button, add the desired telemetry variables to one of the telemetry vectors Data to VApp.

	l <mark>ılıl</mark> Telemetry	- × • • • • •
▼ 🕂 Telemetry	Search Freq 10.0 Hz Address App 2 + Hash: 0x0	
[16%] Data to VApp	Enabled	Fields: 20 / 600
— [0%] Data to VApp		
[0%] Data to VApp		
[0%] Onboard Log		
[0%] User Log		
-		
Sniffer		
[0%] Sniffer 1		
	IAS (Indicated Airspeed)	Ć
	TAS (True Airspeed)	
	GS (Ground Speed)	
	Heading	
	Flight Path Angle	
	 Telemetry [16%] Data to VApp [0%] Data to VApp [0%] Data to VApp [0%] Onboard Log [0%] User Log [0%] Fast Log [0%] Fast Shiffer 	Lift Telemetry



(i) Note

For further information about this Telemetry menu, please refer to the Telemetry section of **1x PDI Builder** user manual.

- 3. Configure the Data to VApp vector where the variables have been added as follows:
 - Frequency: Desired frequency of data transmission
 - Address: App 2 (Veronte apps address)

i Note

Hash parameter is not configurable, it is automatically calculated by the system based on the telemetry vector configured by the user. It is a hexadecimal representation of the CRC of the fieldset.

1x 4.8		.ill Telemetry	8 2 8 0
Ö	▼ 🕂 Telemetry	Search Freq Hz Address App 2 🔻 Hash: 0x6d57a340	
\bigotimes	[23%] Data to VApp	Enabled	Fields: 25 / 600
	[5%] Data to VApp	- 🗣 🛧 📴 Relative Timestamp	
	- [0%] Data to VApp	- 🗣 🛧 📴 Longitude	
# ◆	[0%] Onboard Log [0%] User Log	- 🖡 🎓 🕞 Latitude	
Q ⁰	[0%] Fast Log		
@			
.∞ 			
		Disabled	
$\begin{tabular}{ c c } \hline \hline \\ $		IAS (Indicated Airspeed)	2
		TAS (Indicated Airspeed)	U
6 20		GS (Ground Speed)	
×		+ Heading	
		Flight Path Angle	~

Data vector parameters

4. Save the changes by clicking 📳 button.

Veronte UDP Telemetry CLI

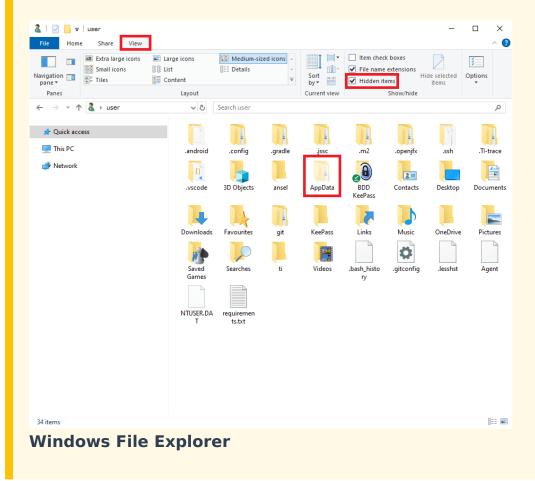
Veronte UDP Telemetry CLI has a configuration file (tudp.config) where
users must specify which telemetry variables to send. Once the app is installed,
this file can be found in C:/Users/user/AppData/Roaming/
VeronteUDPTelemetryCli :



Configuration file

∆ Caution

On Windows, the AppData folder is hidden by default, if it is not visible in C:\Users\user, users can "show" it by checking the "Hidden Items" checkbox:



This configuration file consists of 3 parts:

- **&HEAD** hex. This establishes the header of the UDP messsages sent.
- &LVARS ... END_LVARS . Defines the LVARS, which are complex variables defined by the user, as expressions in which autopilot variables may or may not be used. Each new line between &LVARS and END_LVARS is a LVAR. LVARs can be boolean or number type.

Each LVAR has the following structure: L[id] = [default value] = [expression]

• id : It is any integer to identify the LVAR and is used in the entries to indicate the LVAR to send.

- default value: The default value is the initial value that the LVAR will have the first time it is set.
- expression: For each UDP packet sent, the LVAR values are updated with the result by evaluating the expression.

Example

L40 = false = (u1599_RVAR_1021 > (0.5)) & (u1599_BIT_1053 > (0)) LVAR L40, initialized as **false**, and for each UDP packet sent, the LVAR value is updated with the result of the expression (u1599_RVAR_1021 > (0.5)) & (u1599_BIT_1053 > (0)).

Where, u1599_RVAR_1021 refers to RVAR 1021 of the autopilot with address 1599, and u1599_BIT_1053 refers to BIT 1053 of the same autopilot.

• **Offsets/Entries**. This is the information that is sent via UDP for each telemetry variable.

Users must fill in for each entry (except bits) the following fields of the table in **this order**:

1. **MULT** (float): Scaling factor by which the variable obtained from the autopilot is multiplied.

(i) Note

Only used for the following **VVARs** (VERVARs): L_EQ, RVAR, UVAR, CUSTOM and LVAR.

This field does not affect the bits, but must be set nonetheless.

 OFFSET (float): Offset factor to be added to the variable value obtained from the autopilot, before being multiplied by the MULT value.

(i) Note

This field does not affect the bits, but must be set nonetheless.

3. **TVAR**: Type of variable representing the value sent via UDP. It can be:

() Important

The variables configured in the tudp.config file must match the previous configuration from 1x PDI Builder configuration section of this manual, so each variable is parsed according to the organization of the bits.

- **byte**: Unsigned byte (0 to 255)
- **bit**: A desired number of bits
- **UInt16**: Unsigned 16-bit integer (0 to 65.536)
- Int16: Signed 16-bit integer (-32.768 to 32.768)
- **UInt32**: Unsigned 32-bit integer (-2.147.483.648 to 2.147.483.648)
- Int32: Signed 32-bit integer (0 to 4.294.967.295)
- **Float**: 32 bit single-precision floating-point ($3.4028237 \cdot 10^{38}$ to $1.175494 \cdot 10^{-38}$)

(i) Note

Unlike the other TVARs, **bits** allows users to define several variables that are packed as only one within the UDP message. To do this, each new line is a variable that is included in the bits entry, until the <u>&END_BIT</u> line is read.

 UAV (int): Serial Number of the Autopilot 1x where the variables come from.

i Note

UAV address does not matter for LVARs, since it is either already indicated in the LVAR expression or it is a value that does not come from any autopilot.

- 5. **VERVAR/VVAR**: Type of variable in Veronte system.
 - **RVAR**: Real variables obtained **directly from the autopilot**
 - UVAR: Integer variables obtained directly from the autopilot
 - BIT: Bit variables obtained directly from the autopilot
 - CUSTOM
 - **NONE**: Equivalent to 0

 L_EQ: Linear equation. Similar to TVAR bits, it allows defining several variables in a single entry.

The resulting value of this type of entry is the addition of all the consequent variables, multiplied by COEFFICIENT, to which the unit conversion (UNIT), addition (OFFSET) and multiplication (MULT) are finally applied.

The linear equation continues to wait for more variables until the &END L_EQ line is read.

(i) Note

As implemented, there is no use for the ID field when defining an L_EQ, since the IDs used are those of the following lines.

- **LVAR**: It must be previously defined as explained above.
- ID (int): Identifier of the variable in Veronte. Refer to the Lists of Variables - Lists of interest section of 1x Software Manual for Index-Variable correspondence or check it on the Variables panel of the UI menu of 1x PDI Builder app.
- 7. **UNIT** (int): Index of the unit of measurement of the variable in case a conversion has to be made.

Please, see the Index-Unit correspondence table for detailed information.

- LIMITS (optional) (Only for BITs): It is optional and its format is [min&max], both are of float type.
- 9. **COEFFICIENT** (Only for L_EQ): It is a coefficient of the linear equation.

Below are several examples of the configuration file depending on the type of variable to be sent.

• **RVARs**. Example with Relative Timestamp, Longitude and Latitude variables:

	#HEAD HEX &HEAD 0AA0					
#MULT 1000 1	OFFSET 0 0	TVAR UInt32 Float	UAV 1599 1599	VERVAR RVAR RVAR	ID 300 500	UNIT NONE NONE
1 NONE	Θ	Float	1599	RVAR	501	
(4 bytes) # Second	<pre>NONE # First row: Send Time Since Hardware Start-Up (Milliseconds) as an UInt32 (4 bytes) # Second row: Send Longitude as a Float (4 bytes) # Third row: Send Latitude as a Float (4 bytes)</pre>					

• LVARs:

```
#HEAD HEX
&HEAD
        1FB9
&LVARS
L1 = 0 = L1 + 1
L70 = 20 = L70 + L1
L45 = false = L70 % 2 == 0
L80 = false = (u1599_RVAR_1021 > (0.5)) && (u1599_BIT_1053 > (0))
&END_LVARS
# L80 initially has a value of false. Next values are obtained from the
expression
# (u1599_RVAR_1021 > (0.5)) && (u1599_BIT_1053 > (0))
# u1599_RVAR_1021 = value of RVAR 1021 (stky21, Stick Input y21)
# from autopilot with address 1599.
# The value of this variable is also updated every time
# Use of Lvars
#MULT
            OFFSET
                        TVAR
                                         UAV
                                                     VERVAR
                                                                 ID
                                                                         UNIT
1
            0
                        Int16
                                         0000
                                                     LVAR
                                                                 1
                                                                         NONE
1
            0
                        Float
                                         0000
                                                     LVAR
                                                                 70
                                                                         NONE
                                         0000
                                                     LVAR
                                                                         NONE
1
            0
                        byte
                                                                 45
# UAV address does not matter for these LVARs since they do not come from an
autopilot.
# First row: Send L1 as an Int16 (2 bytes)
# Second row: Send L70 as a Float (4 bytes)
# Third row: Send L45 as a byte (1 byte)
```

• BITs:

	AA0					
#MULT	OFFSET	TVAR	UAV	VERVAR	ID	UNIT
1	Θ	bits				
#UAV	VERVAR	ID	UNIT	LIMITS(optiona	l)	
1599	RVAR	501	NONE			
1599	RVAR	500	NONE	[-1000&1000]		
&END_BIT						
# Mult an	d Offset do	not affect	bits, but the	y must be set reg	ardless.	

• **BITs with LVARs**. Taking the LVARs defined in the previous example:

```
#HEAD HEX
&HEAD
        1FB9
#Definition of LVARs
&LVARS
L1 = 0 = L1 + 1
L70 = 20 = L70 + L1
L45 = false = L70 % 2 == 0
&END_LVARS
#Bits example with lvars
#MULT
            OFFSET
                        TVAR
                                         UAV
                                                     VERVAR
                                                                 ID
                                                                          UNIT
1
                        bits
            0
#UAV
            VERVAR
                        ID
                                     UNIT
                                                 LIMITS(optional)
0000
            LVAR
                                     NONE
                        1
                                                 [0&10]
                        70
0000
            LVAR
                                     NONE
                                                 [100&500]
0000
            LVAR
                        45
                                     NONE
&END BIT
# Mult and Offset do not affect bits, but they must be set regardless.
# Any int value is valid and acts the same.
# In this example, each one of the variables occupies one bit in the
resulting message.
# L1, which is incremented by one, is checked if it is within the set limit
0&10,
# i.e., for values strictly greater than 0 and strictly less than 10,
# the bit will be 1, and for all other values, it will be 0.
# The same applies to L70, when 100<L70>500, the bit is 1, and for the rest
it is 0.
# L45 on the other hand doesn't have a limit.
# When no limit is established, it compares it to 1.
# Since L45 is a boolean that checks that L70 is even,
# the bit will be one when the value is 1, and 0 when not.
# Concrete example: L1 = 16, L70 = 156, L45 = true (because L70 is even)
# The UDP packet will be:
# HEADER: 31 -71
# L1: 16 0
# L70: 0 0 28 67
# L45: 1
# bits: 6 = bits[1 1 0] because:
# L1 is not in the limits (0), L70 is (middle 1), and L45 is 1/true (left
1).
```

```
\ensuremath{\#} The order is from least to most significant in the order indicated in the bits list.
```

• L_EQ:

#HEAD HEX	X 0AA0					
#MULT	OFFSET	TVAR	UAV	VERVAR	ID	UNIT
1	Θ	Int16	0000	L_EQ	NONE	NONE
#UAV	VERVAR	ID	UNIT	COEFFICIENT		
1001	RVAR	1	NONE	2.3		
1001	UVAR	1	NONE	2.3		
&END_L_E	Q					
# ((COEF	EQUATION: FICIENT*RVAR(RVAR(1) + 2.3		ICIENT*UVAR(1)) + 0) * 1	+ Offset) * Mu	ult	

• **L_EQ with LVARs**. Taking the LVARs defined in the previous example:

```
#HEAD HEX
&HEAD
        1FB9
#Definition of LVARs
&LVARS
L1 = 0 = L1 + 1
L70 = 20 = L70 + L1
&END LVARS
#Linear equation example with lvars
#MULT
            OFFSET
                        TVAR
                                         UAV
                                                      VERVAR
                                                                  ID
                                                                          UNIT
2
            13
                        Float
                                         0000
                                                      L EQ
                                                                  0
                                                                          NONE
#UAV
            VERVAR
                        ID
                                     UNIT
                                                 COEFFICIENT
0000
            LVAR
                        1
                                     NONE
                                                  50
0000
            LVAR
                        70
                                     NONE
                                                  25
&END_L_EQ
# Concrete example: L1 = 1, L70 = 21
# ((50*L1 + 25*L70) + Offset) * Mult = ((50*1 + 25*21) + 13) * 2 = 1176
# Sent as a Float, therefore in the udp packet it will be:
# 1176 = [0 \ 0 \ -109 \ 68]
```

Index-Unit correspondence table

Unit ID	Unit
0	m/s
1	kt
2	km/h
3	mph
4	ft/s
121	ft/m
321	mm/s
5	m

Unit ID	Unit
6	km
62	mm
63	cm
7	mi
8	NM
9	yd
10	ft
11	in
12	m/s²
13	ft/s²
14	in/s²
15	g (gravity)
202	rad
16	rad [$-\pi$, π]
203	rad [0, 2π]
205	Q
17	º [-180,180]
101	⁰ [0,360]
102	<u>0</u> י יי
103	º ' '' (N/S)

Unit ID	Unit
104	♀ ' '' (E/W)
21	Т
160	nT
23	G
22	mG
24	V
25	mV
26	А
27	mA
340	kA
28	Ра
29	kPa
30	bar
31	mbar
32	psi
33	mmHg
34	at
35	atm
147	Pa ²
36	к

Unit ID	Unit
37	₀C
38	٩F
39	S
120	Time
40	min
41	h
330	ns
108	μs
109	ms
42	rad/s
117	º/s
43	rad/min
44	rad/h
45	rps
46	rpm
47	rph
57	m³/s
58	gal/s
54	gal/h
59	l/s

Unit ID	Unit
55	l/h
56	
60	x1
64	%
61	pkts/s
105	Hz
106	mHz
107	kHz
140	Bd
141	kBd
142	MBd
110	m²
111	Cm²
112	mm²
113	km²
114	mile ²
115	ft²
116	yd²
118	bit
119	byte

Unit ID	Unit
131	KB
132	GB
122	kg
123	g
124	tonnes
125	lbs
126	oz
127	Ν
128	kN
129	lbf
130	pdl
134	rad/s²
135	rad/min ²
136	rad/h²
137	⁰/S²
138	⁰/m²
139	⁰/h²
329	rpm/s
143	T ²
144	(m/s)²

Unit ID	Unit
145	(cm/s)²
146	(mm/s)²
327	Ω
328	Henrios
322	watios
323	kW
324	Kgm/s
325	erg/s
326	cv
331	m³
332	dm³
333	mm³
334	L
335	mL

Operation

This section details the steps to **transmit telemetry UDP messages** through **Veronte UDP Telemetry CLI**.

Sending UDP messages

Veronte UDP Telemetry CLI connects to **Veronte Link** to send the previously configured Autopilot 1x telemetry via UDP messages. For this reason, the connection between the autopilot and **Veronte Link** must be properly established, and **Veronte Link** needs to be opened.

i Note

For more information about this connection, please refer to Connection - Operation section of this manual.

These are the options to send the configured variables:

 Launching Veronte UDP Telemetry CLI by double-clicking on the App shortcut or the .exe file:



Veronte UDP Telemetry CLI shorcut

This will send the UDP messages with the following default configuration:

- **Host url**: 127.0.0.1
- **UDP port**: 3000
- Frequency: 10 Hz

(i) Note

These installation files location will vary depending on the location selected during installation.

Note that Veronte UDP Telemetry CLI Installer.exeVeronte UDP Telemetry CLI.exe.exeto launch.

- 2. Launching **Veronte UDP Telemetry CLI** .exe from terminal, where it is possible to specify the parameters of the trasmission using the following command-line options:
 - - u: UDP address
 - - **p**: UDP port
 - $\circ\,$ f: Desired frequency of data transmission (Hz)

This is an example:



Launching from terminal example

The expected outcome is the following:

o veronte-udp-telen	metry-cli-6.12.1			-	×
[34m2023-12-05 [34m2023-12-05 [34m2023-12-05 [34m2023-12-05 [34m2023-12-05	10:18:13 10:18:13	[INFO] [INFO]	Starting Veronte-UDP-Telemetry RUNNABLE Trying to connect with vlink Client deployed and connected to vlink. UAVINI# 1x v4.8 4041 (6.12.69) ADD		

Expected outcome

(i) Note

Veronte UDP Telemetry CLI always adds the matcher 0x0A 0xA0 at the beginning of each sent UDP packet before the variable data.

Therefore the received UDP packet will be: 0x0A 0xA0 followed by the consecutive stream of data in the order and byte width configured in tudp.config.

If users have any doubts about the UDP packets that are generated, please refer to Viewing UDP data - Troubleshooting section of this manual.

Operation

In order to establish a connection between a Veronte device and a PC with **Veronte Link**, follow the steps:

1. Connect the device to a PC via Serial (USB, RS232 or RS485) or UDP/TCP (Wifi or Ethernet).

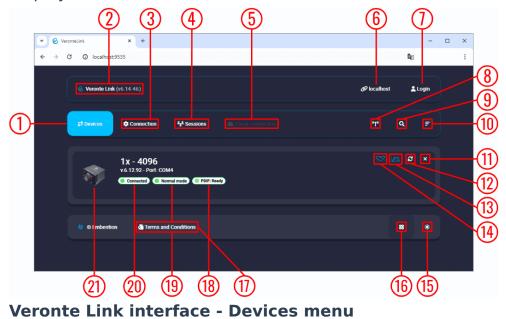


PC-Veronte device connection

(i) Note

Connecting the device to the PC is not necessary when communicating via Veronte Cloud. Please, see Cloud connection for further information.

Open Veronte Link, then a similar image to the following should be displayed:



1. **Devices**: This is the currently displayed menu. It shows the devices connected to the PC.

- 2. **Veronte Link version**: Informs the user about the version of the software being used.
- 3. **Connection**: This menu allows the user to configure the connection between the PC and a Veronte device. See Connection section for more information.
- 4. **Sessions**: In this menu users can play back recorded logs and flights. See Sessions section for more information.
- Cloud connection: This menu allows the user to configure the internet connection between the PC and the available Veronte Autopilots 1x.

See Cloud connection section for more information.

(i) Note

Only available if the user has logged in.

- 6. **Host**: Allows connecting to the local IP address or to another desired IP address.
- 7. Login: Enables cloud connection through user logging.
- 8. Find all: Runs a discovery to all devices.
- 9. **Search from ID**: Searches for a specific device by its ID. Entering the ID **999** will search for all devices.
- 10. **Sort list**: Click on it to sort the list of devices.
- 11. **Remove device**: Only works after disconnecting the device.

(i) Note

Only available if a device is connected or has been connected.

12. **Refresh configurables**: It is recommended to use in case of any connection error.

i Note

Only available if a device is connected or has been connected.

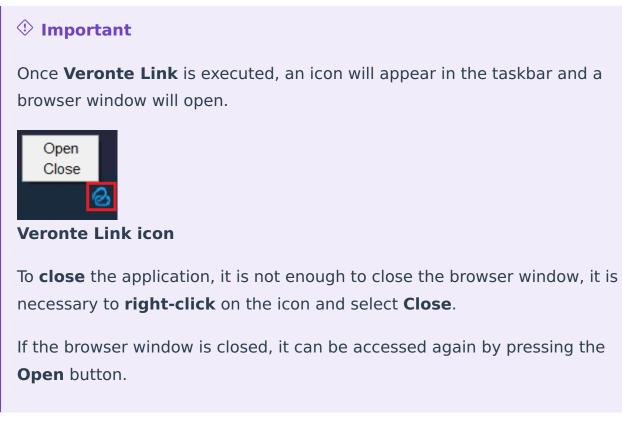
13. **Open Veronte FDR**: From here users can access Veronte FDR on the same version of the connected device.

- 14. **Open Veronte Ops**: From here users can access Veronte Ops on the same version of the connected device.
- 15. **Dark/light mode**: Switches to light/dark mode, changing the display mode of the interface.
- 16. **Switch particles**: Particles can be on or off, changing the application appearance.
- 17. **Terms and Conditions**: Users can consult the 'End User License Agreement (EULA)' by simply clicking on this button.
- 18. **Configuration status**: It can be:
 - PDIF: Waiting to read
 - PDIF: Reading
 - PDIF: Ready
 - PDIF: Failed load
 - PDIF: Not Downloaded (for products other than Veronte Autopilot 1x)
 - PDIF: Not compatible

(i) Note

Products are typically operational even if the configuration is not marked as "ready".

- 19. **Device status**: Can be in Normal mode, Maintenance mode or Loaded with errors.
- 20. **Connection status**: It can be Connected or Disconnected.
- 21. **Veronte device**: Here it is displayed an image of the Veronte device that is connected.



Connection

In this menu users must **configure the connection type** of the Veronte device.

	Vero	nteLink		× +							-		×
← →	C	O localhos	st:953	5/?host=local	nost&na	av=connection				G	E		:
	1											~	
		🗟 Veronte Lini	k						Ø localhost		💄 Login		
		₽ Devices		Connection		°ढ ़° Sessions				+	Ŧ		
		No connec	ctior	ns found									
		👂 © Embentic	on	ot Term	s and C	conditions				88	*		

Connection menu

Clicking on the '+' icon will display the **configuration** panel. The parameters to be configured depend on the type of connection selected:

∆ Warning

Apart from **Type** and **Port** parameters, it is not recommended to modify the default configuration, as the default parameters should work correctly.

• **Serial**: USB, RS232 or RS485 connections.

٤	ERIAL	_		•
SI	ERIAL conf	iguration		
F	Port			•
	audrate			•
	Parity			
	IONE			•
	IONE			•
a a	lata bits			•
	top bits			-
		_	_	
	Advanced		^	•
p.	5		×	
	C Disconnect time		×	
		Cancel	Sav	

Serial connection configuration

 Port: Select the port of the computer to which the device is connected.
 It does not have to be the same as the one in the example image (Veronte Link interface).

More information about the port where the device is connected is explained in Serial connection - Integration examples section of the present manual.

- **Baudrate**: This field specifies how fast data is sent over a serial line.
- **Parity**: Is a method of detecting errors in transmission.

When parity is used with a serial port, an extra data bit is sent with each data character, arranged so that the number of 1 bits in each character, including the parity bit.

The available options are EVEN, MARK, ODD, SPACE and NONE.

- Flow control: RTS/CTS and XON/XOFF control can be configured if needed.
- Data bits: Defines the number of bits in the message. It can be configured from 5 to 8 bits.
- Stop bits: Number of stop bits sent at the end of every character. Can be 1, 1.5 or 2.
- Advanced:
 - Reconnect time: The time to consider a device reconnected.
 Default is set to 5 seconds.
 - Disconnect time: Time to consider a device disconnected is defined here. 1 second is configured by default.

(i) Note

In case of not getting the device connected, make sure that the PC acquires a communication port.

• **UDP**: Ethernet or Wifi connections.

UDP	•
UDP configuration	
Address	
239.0.0.1	
- Port	
12345	
TTL	×
Buffer size	

UDP connection configuration

() Important

Consider the maximum packet size supported by the Veronte Communication Protocol (VCP) when using serial data converters.

- Address: IP address, normally set to 239.0.0.1 (for broadcast) or 127.0.0.1 (for local).
- **Port**: IP Port must be set.

 TTL: Time To Live, it is the maximum amount of time or 'hops' that a UDP packet can exist inside a network before being discarded by a router.

A default value should automatically be set.

 Buffer size: Users would have to increase or decrease this value depending on the number of devices sending information through this channel.

By default this parameter has a value of **300**, which is the maximum value of a VCP message.

Explanation

For example, if a PCS is connected by radio to an Autopilot 1x, the buffer size should be increased because more consecutive messages arrive and can be mixed between them, generating invalid messages that cause messages to be discarded.

(i) Note

How to establish a connection via UDP is detailed in the UDP connection - Integration examples section of the present manual.

• **Planet**: Satellital connections, it requires internet connection.

New connection
PLANET
PLANET configuration
ACID (SATCOM ID)
Cancel Save

Planet connection configuration

- Satcom ID must be set.
- **TCP-SERVER**: Ethernet or Wifi connections.

Type *		•
CP-SERVER	configurat	ion –
	connguiat	
3000		
Buffer size		
300		

TCP-SERVER connection configuration

- **Port**: Set the TCP port from which the devices will get the information provided by Veronte Link.
- Buffer size: Users would have to increase or decrease this value depending on the number of devices sending information through this channel.

By default this parameter has a value of **300**, which is the maximum value of a VCP message.

Explanation

For example, if a PCS is connected by radio to an Autopilot 1x, the buffer size should be increased because more consecutive messages arrive and can be mixed between them, generating invalid messages that cause messages to be discarded. Otherwise, if a very high buffer size is set, and only one device sends messages, the buffer will take longer to fill up, thus generating a delay in the reception of messages.

i Note

How to establish a TCP-SERVER connection is detailed in the TCP-SERVER connection - Integration examples section of this manual.

• **TCP-CLIENT**: Ethernet or Wifi connections.

TCP-CLIENT	•
CP-CLIEN	tion
Address	
192.100.100.1	 _
Port	
20002	
Buffer size	
300	
	_

TCP-SERVER connection configuration

- **Address**: Enter the address of the device from which Veronte Link has to obtain the information.
- **Port**: Enter the TCP port from which the information is obtained.
- Buffer size: Users would have to increase or decrease this value depending on the number of devices sending information through this channel.

By default this parameter has a value of **300**, which is the maximum value of a VCP message.

Explanation

For example, if a PCS is connected by radio to an Autopilot 1x, the buffer size should be increased because more consecutive messages arrive and can be mixed between them, generating invalid messages that cause messages to be discarded.

i Note

How to establish a TCP-CLIENT connection is detailed in the TCP-CLIENT connection - Integration examples section of this manual.

Finally, click on **Save**.

Sessions

Sessions tab displays all **finished** device sessions.

Important

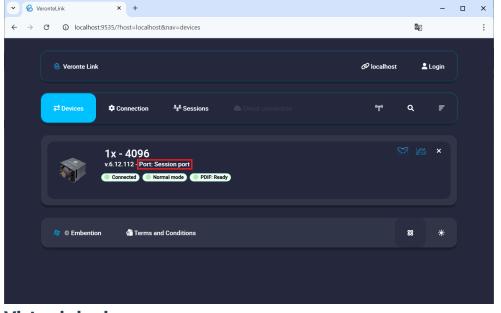
- Sessions that are currently being recorded will not be displayed.
- A session from the currently connected device cannot be replayed.
- If users experience problems when attempting to replay a session, please check the Error when replaying a session Troubleshooting section of this manual.

The following image and list describe each functionality.

	•	0	/eronte	Link		:	× +														-		×
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				Vero	nte Link	(v6.14.	28)											Øloca	alhost		💄 Login		Î
			Ŧ	[≱] Devic	es	¢c	connection	n	<mark>ిం</mark> Sess	ions National Anna Anna Anna Anna Anna Anna Anna A													I
													Items	per pag	e: <u>5</u>	-	1 – 5 o	f 62			> >I		I
\bigcirc				4	ession 096_2 9.47 мв		05.30. 11m:38s	10.31	.48	Player	•												l
					041_2 29.61 мв		05.29.	13.57	7.34	/	-	×	0										
_		_		(3	(4			(5)(6)(D			(3)						

Sessions menu

- 1. Session name: It is made with recording time (date and hour).
- 2. Delete session. If the user wishes to delete more than 1 session at a time, it is possible to delete them from the Veronte Link sessions folder located in the following path: C:\Users\USER NAME\AppData\Roaming\VeronteLink\sessions
- 3. Files weight.
- 4. Duration.
- Play/Pause: Play button creates a virtual device in the "session port" similar to the following figure:



Virtual device

It starts a simulation replaying everything that happened during the session recording. It will recreate all the ocurred events with detail and **Veronte Ops** will display the corresponding data and trajectories; read the Veronte Ops user manual for more information.

(i) Note

In addition, when the virtual device is in a **ready** state, users can open the 1x PDI Builder software and download the configuration (PDI files).

- 6. **Stop**: It stops playing the session. It **does not delete the session**.
- 7. **Speed**: Playing speed can be selected as x0.5, x1, x2, x4 and x8.



8. **Display bar**: Click and drag to replay any moment.

Cloud connection

Cloud connection tab allows the user to connect to a Veronte Autopilot 1x through **LTE network**. This functionality is enabled thanks to the **HSPA+** module (internal or external) embedded in Veronte autopilots.

(i) Note

To activate the internal card or Veronte Cloud data traffic through internet, please contact sales@embention.com. Remember that there is **no internet connection** when **HSPA+ module** is deactivated.

To configure this type of connection, these steps must be followed:

∆ Warning

In order to set up and operate a Veronte Autopilot 1x via Cloud connection, users must **first**:

- 1. Log in Cloud.
- 2. Establish a connection to Autopilot 1x that is not through Cloud (Serial, UDP, TCP-Server or TCP-Client).
- 3. **Upload** PDIF (configuration) to 1x with the **1x PDI builder** app or with the **Upload PDIFs to cloud** button

This button will work as long as the cloud device is connected and the PDIFs are in the Ready state otherwise it will show errors:



Now the users are ready to establish the connection via Cloud and work. If these steps are not followed, Autopilot 1x will be in **PDIF: Failed load** status.

(i) Note

This only needs to be done once per Veronte Autopilot 1x and per configuration.

1. **Login**: After clicking the Login button, users must introduce their associated username and password.

🔗 Veronte Link			Ø localhost	Login
로 Devices ✿ Connection ** Session	IS Cloud connection		۳ ¹ (רא <i>ד</i>
1x - 2477 v.6.12.68 - Port. COM5 Connected Mormal mode	POIF: Ready			æ ×
© Embention Onditions			8	8 *
	Login			
	Lusername	×		
	Password	Ø		
		Cancel Login		

Cloud Connection: Login

(i) Note

Login credentials are automatically assigned. In case they have not been provided to you, please contact the support team by creating a ticket in the customer's Joint Collaboration Framework; for more information, see Tickets section of the JCF manual or contact sales@embention.com.

2. **Open Cloud connection tab**. Veronte Autopilots 1x linked to user's account should be displayed.

🔗 Veronte Link					Ø localhost	👗 User name
₽Devices	Connection	్రి Sessions	Cloud connection			e
4085 Last connection:	Not previously conne	cted	4 • >	1792 Last connection: Not previously connect	ed	۵ 🌒
1793 Last connection:	Not previously conne	cted	۵. 🕒	4087 Last connection: 2/4/25, 3:48 PM		\$
2 © Embention	on Terms an	d Conditions				88 *

Cloud Connection: Available devices

The following information is displayed for each autopilot:

• ID: Identification number of the autopilot (Serial Number).

- **Last connection**: Indicates the date on which the last connection to that device was established.
- Activate the connection with the desired Autopilot 1x by turning on the toggle button displayed next to it.

\delta Veronte Link					Ø localhost	👗 User name
₽ Devices	Connection	<mark>°</mark> Sessions	Cloud connection)		æ
4085 Last connection:	Not previously conne	cted	•	1792 Last connection: Not previously connected		4 •
1793 Last connection:	Not previously conne	cted	a O	4087 Last connection: 2/4/25, 3:48 PM		۵ 🔿
© Embention	n 🔊 Terms and	d Conditions				88 *

Cloud Connection: Connect to an Autopilot 1x

i Note

Since Cloud connections are based on **LTE communication**, this connection may not be immediate. The selected autopilot will only be displayed in the 'Devices' tab when it is succesfully connected.

 At this point, Veronte Link must have established the connection with the selected Autopilot 1x. Consequently, the autopilot must be displayed in the Devices tab.

(i) Note

Since Cloud connections are based on **LTE communication**, **connection may be lost** even when the toggle button is on. In this case, the autopilot will disappear from the 'Devices' tab, appearing again when the connection is retrieved.

5. Log out: Click on the username to enable the log out button, and then press it.

S Veronte Link					Ø localhost	User name
₽ Devices	Connection	ዩ ዮ Sessions	Cloud connection)		〔↔ Logout
4085 Last connection:	Not previously conne	cted		1792 Last connection: Not previously connected		۵.
1793 Last connection:	Not previously conne	cted	۵.	4087 Last connection: 2/4/25, 3:48 PM		A D
2 © Embention	🔊 Terms and	d Conditions				88 *

Cloud Connection: Log out

Integration examples

Serial connection

As the com port configuration is common to all devices, the following steps are applied to MC24 and MC110 controllers as an example.

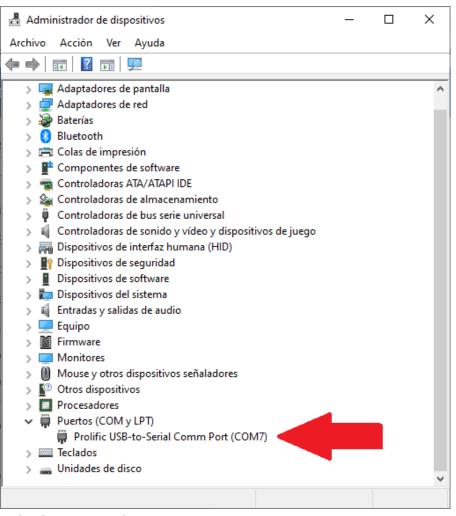
1. Once **Veronte Link** is installed, the first step that must be done is to set the connection that your MC unit is currently using.

By default, every MC is capable to comunicate through USB, RS232 and RS485 so any of these can be used (properly adapted to USB/serial). First, click on "+":

⇄ Devices	Connection	ዩ ያ Sessions	Cloud connection		+	3
	•	•				
No connect	tions found					
				۰		
🧳 © Embentio	n 👌 Terms an	nd Conditions			88	(

Add new connection

 Besides, it is required to find out which port is employing the MC unit.
 Windows allows to do that with the **Device Manager** from the **Control Panel**.



Windows Device Manager

3. Select your COM settings by entering the **Comm Port** previously found. Normally, the other default parameters should not be changed.

New connection	
SERIAL Type *	
SERIAL configuration	
Сом7 -	
Baudrate 115200	
NONE	
Flow control	
Bata bits	
Stop bits	
Cancel Save	

New connection configuration

 If the selected port is correct and everything went well, a new MC will be displayed in the devices list. However, the device status will remain as **PDIF: Waiting to read**. The user is ready now to start configuring the motor controller using **MC PDI Builder**.

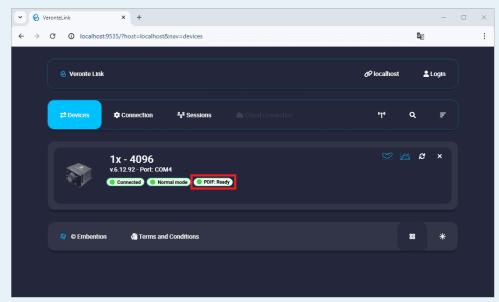
	Connection	°,१ Sessions	Cloud connection	(· † *)	Q	=
₽ Devices			Cioud connection	.1.	4	=
					88 109	а×
8	MC 110 - 999 v.6.12.47 - Port: COM7				~ _	-
	Connected Normal mode	PDIF: Waiting to read				
🙋 © Embe					~	
	ntion 🕺 Terms and	d Conditions			88	

MC unit correctly connected

More Veronte devices (MC units, Veronte Autopilots, etc.) could be added following these instructions.

(i) Note

In case of connecting a Veronte Autopilot 1x, after a few seconds, the device status should replace **PDIF: Waiting to read** by **PDIF: Ready**, since **only Autopilot 1x is able to change or load configuration in normal mode**.



Veronte Autopilot 1x connected and ready

For Veronte devices other than 1x, **PDIF: Waiting to read** should be replaced by the status **PDIF: Not Downloaded**.

UDP connection

Wi-Fi/Ethernet configuration

The following steps are applied to a **PCS** unit as an example.

() Important

If connecting through Ethernet, step 1 does not apply.

- 1. The first step is to look under available networks for the PCS unit and connect to it.
- Once the connection is made, enter Veronte Link and configure the UDP connection in the Connection menu.

First, click on "+":

 ✓ ⊗ Verc ← → (- ©g		×
(ô Veronte Link	Ø localhost	👱 Login)	
	₽ Devices ₽ Connection 1.1 Sessions 40. Cloud connection		± ₹		
	No connections found				
	Ø Embention Ø Terms and Conditions		88 *		
Add	new connection				

3. Then, the configurable parameters must be entered.

UDP		•
JDP confi	guration	
Address		
239.0.0.1		
Port		
12345		
		_
TTL		×
Buffer size —		
300		

New UDP connection configuration

Important

This address and port are configured for this PCS unit, they do not have to be the same for another device.

 Finally, if the configured connection is correct and everything went well, a new PCS will appear in the device list and the device status will change to **PDIF: Ready**. The user is ready now to start configuring the PCS using **1x PDI Builder**.

Verontelink X +	– 🗆 X
← → ♂ ۞ localhost:9535/?host=localhost&nav=devices	🔄 🛞 Invitado
S Veronte Link (v6.14.28)	Ø localhost ≜Login
Connection [*] * Sessions	°T° Q <i>≡</i>
1x - 4159 v6.12.112 - Port: UDP / 192.168.8.2:54321 Connected Normal mod PDIF: Ready	SS 🙇 🞜 ×
© Embention Terms and Conditions	88 *

PCS unit correctly connected

(i) Note

The image of a Veronte Autopilot 1x is displayed and not a PCS as the device that is actually connected is the Autopilot 1x inside the PCS.

TCP-SERVER connection

Ethernet configuration

The following steps detail how to connect Veronte Link to an Autopilot 1x via a TCP connection to a **Microhard** radio.

(i) Note

In this connection, the **radio** acts as "**Client**" and **Veronte Link** as "**Server**".

- Configure, in the Microhard WebUI, the radio as "TCP Client" and enter the following parameters:
 - **Remote Server IP Address**: IP address of the PC.
 - Remote Server port: TCP port to which the radio has to connect. It must be the same as the one configured in Veronte Link.

For more information on the radio configuration, users can refer to the Microhard radio configuration - Integration examples section of the **1**x **Hardware Manual** or directly to the Microhard radio documentation.

- Connect Veronte Autopilot 1x to the Microhard radio via RS232 as detailed in the Microhard pDDL900-ENC external - Integration examples section of the 1x Hardware Manual.
- Once the configuration and connection is done, open Veronte Link and configure the TCP-SERVER connection in the Connection menu.
 First, click on "+":

VeronteLink	x +		-	×
← → C ③ localhost:9535/	?host=localhost&nav=connection	<u>G</u> e		:
🔗 Veronte Link		Ø localhost	Login	
₽ Devices	Connection	+	Ŧ	
No connections	found			
Implementation Implementation	d) Terms and Conditions	8	*	

Add new connection

4. Then, the configurable parameters must be entered.

ľ	New connection
ſ	Type *
	TCP-SERVER TCP-SERVER
)
	CP-SERVER configuration
ſ	Port
	20002
	Buffer size
	300
	Cancel Save

New TCP-SERVER connection configuration

- Port: Enter a TCP port to which the radio will be connected, the same as the one previously configured as "Remote Server port" in the radio configuration.
- 5. Finally, if the configured connection is correct and everything went well, a new Autopilot 1x will appear in the Devices list. It should look like this:

👻 🙆 v	erontelink × +		- 🗆 X
$\leftarrow \rightarrow$	C O localhost:9535/?host=localhost&nav=devices	₫ <mark>2</mark>	:
	🗞 Veronte Link	Ø localhost 💄	Login
	Z ² Devices Connection ⁺ ⁺ Sessions	nnection 🙌 Q	F
	1x - 4096 v.6.12.92 Port: TCP-Server /192.168.168.1:20002 Connected Normal mode PDIF: Ready	S2 🙇 2	×
	© Embention	83	*

1x unit correctly connected

TCP-CLIENT connection

Ethernet configuration

The following steps detail how to connect Veronte Link to an Autopilot 1x via a TCP connection to a **Microhard** radio.

(i) Note

In this connection, the **radio** acts as "**Server**" and **Veronte Link** as "**Client**".

 Configure, in the Microhard WebUI, the radio as "TCP Server" and enter a "Local Listening Port" to which Veronte Link will have to connect (usually the default one is used).
 For more information on the radio configuration, users can refer to the

Microhard radio configuration - Integration examples section of the **1**x Hardware Manual or directly to the Microhard radio documentation.

- Connect Veronte Autopilot 1x to the Microhard radio via RS232 as detailed in the Microhard pDDL900-ENC external - Integration examples section of the 1x Hardware Manual.
- 3. Once the configuration and connection is done, open **Veronte Link** and configure the **TCP-CLIENT** connection in the **Connection menu**.

First, click on "+":

🗸 🔗 Vero	nteLink 3	× +			-		×
\leftrightarrow \rightarrow (0 localhost:9535/?	?host=localhost&nav=connecti	on				:
(~	
	🔗 Veronte Link			Ø localhost	💄 Login		
	₽ Devices	Connection % Session	ns 🔹 Cloud connec	l i i i i i i i i i i i i i i i i i i i	+ =		
6							
	No connections	found					
	🔊 © Embention	Terms and Conditions		1	8 *		



4. Then, the configurable parameters must be entered.

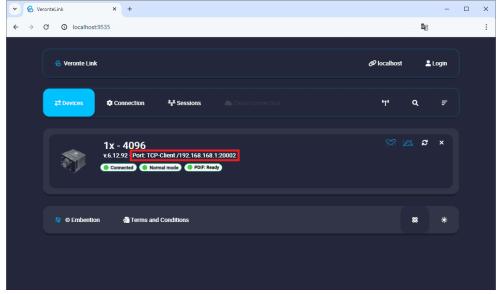
Type *	•
TCP-CLIEN1	Г configuration
← Address	
192.168.168.1	
Port	
20002	
Buffer size	
300	

- Address: IP address of the radio.
- **Port**: Enter as TCP port the "Local Listening Port" previously set in the radio configuration.

() Important

This address and port are configured for this radio unit, they do not have to be the same for another device.

5. Finally, if the configured connection is correct and everything went well, a new Autopilot 1x will appear in the Devices list. It should look something like this:



1x unit correctly connected

Troubleshooting

In case of any software error, it is possible to extract and analyze files from session folder.

△ Warning

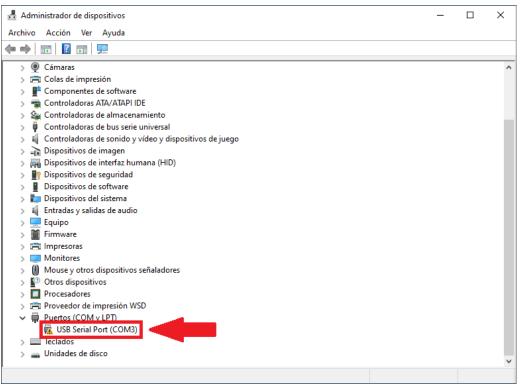
Do not modify or delete manually any **Veronte Link** file. Copy them to a different path to send or analyze.

Veronte Link files are placed on the following paths:

- C:\Users\USER NAME\AppData\Roaming\VeronteLink\configurables Device configurations.
- C:\Users\USER NAME\AppData\Roaming\VeronteLink\sessions Session files, it includes flights information.
- C:\Users\USER NAME\AppData\Roaming\VeronteLink\tracelogs Event logs, it includes flights information.
- C:\Users\USER NAME\AppData\Roaming\VeronteLink ⇒ cfg.son
 Veronte Link connections configuration file. If deleted, the configuration will be lost.
- C:\Users\USER NAME\AppData\Roaming\VeronteLink ⇒ vlink.lock
 Internal file that only appears if any instance of Veronte Link is open. If deleted, there will be instability in the system.

Comm Port error in Windows Device Manager

If the following Windows Comm Port error occurs:



Windows Device Manager - Comm Port error

Users must extend the disconnection time to 5 seconds to fix it. To do this:

- 1. Go to the **Connection** menu \rightarrow click on the **\phi** icon to open the COM configuration.
- Open the Advanced parameters drop down menu → modify the Disconnect time to 5 seconds.

	🔗 Veronte Link		Ø ² localhost ▲Login
		New connection	
		Flow control	+ =
	COM5	Bata bits	× 🗈 📢
	•••	1 T	
	😰 © Embention 🛛 🖓 Ter	Advanced ^	8 C
	1	5 X	
*		Cencel Save	

Connection configuration - Disconnect time

If the user is still having problems with this, please contact the support team by creating a ticket in the customer's **Joint Collaboration Framework**; for more information, see **Tickets** section of the JCF manual.

Error when replaying a session

If the following error message appears when attempting to replay a session:



Error message

It is often due to users trying to replay a previous session from the device that is **currently connected**, which is not possible as indicated in the Sessions section.

Viewing UDP data

An application such as Wireshark can be used to visualize raw data sent from Autopilot 1x. Nonetheless, at the beginning, it may show characaters that do not come from 1x, because Wireshark reads all data from the connected port, including protocol information.

To distinguish 1x messages, the user has to search the matcher 0x0A 0xA0 for **Veronte UDP Telemetry CLI**. The matcher indicates the beginning of the data. In the following example, characters marked with blue correspond to 1x, while yellow characters are the UDP protocol structure.

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Software Changelog

This section presents the changes between the previous software version (**v. 6.14.28**) and the current (**v.6.14.60**).

Added

- Buffer size and TTL values configuration parameters for UDP/TCP connections
- Button to upload the device's PDIFs to the cloud (Upload PDIFs to cloud) in the Cloud connection tab
- Show UDP port in the Connection tab